EMOTATOR MODEL 105TSX INSTRUCTION



EMOTO ANTENNA CO., Ltd.

# A HISTRRY OF THE EMOTATOR

	Emoto Antenna Co., Ltd. is an expert manufacturing company which specialize
	in Antenna Rotator.
	We understand the "KNOW HOW" very well and have more experience than any
-	other rotator manufacturers, and producing the Emotator by excellent me-
	chanical and modern electronics technologies.
	Here in Japan, the Emotator is a pronoun of antenna Rotator and we gua-
	rantee that the Emotator can be used almost permanently.
	PLEASE READ THIS INSTRUCTIONS CAREFULLY BEFORE STARTING OPERATION.
	1. Installation must be made as per photograpf which listed at thefront
	page. The Emotator must no be installed top and bottom reverse or
	horizontally.
	2. The wiring of 6-conductor cable must be made properly. At least check
	the wiring 2-times before start operation.
	The packing includings the followings.
	Rotor section 1
	Controller section 1
	Mast clamp(Consists of strap and U-bolts) 1
	Bolt M8 x 25 with spring and flat washer
	for Mast clamp 4
	Bolt M8x 20 with spring washer for foundation 4
	8 Pin US connector plug
	Waterproof case with screw and rubber gasket 1
	Waterproof Cover With Band 1
	Cable Stopper 1
	Instruction Manual



View attached to 105TSX

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## CONSTRUCTION

- 1. The Fotor and rotate reduction mechanism are incorporated in a completely water proof aluminum diecast alloy housing, and it is made in an extremely compact size becuse the housing it self has to rotate.
- 2. The braking system is used special double action SP system.
- The limit switch is operated one revolution, it is made 3. snap action microswitch.
- 4. A Servo Mechanism and our original circuit mechanism have been incorporated in the Model 105TS Circle Controller and designed for simplified operation. The Servo Mechanism has been made so that the electrical as well as the mechanical sections have inter-related functions and is tested. adjusted and aligned before it is shipped from the factory. Tampering with this section may cause permanent damages and recommend that it be not touched.

#### SPECIFICATION

AC 220 Volt 50/60 Hz 50 VA (115 V CANADA ONY) 117V. Power Source Motor Voltage AC24 500 Kg.Cm Rotation Torque 3.000 Kg.Cm Braking force 1 Square meter Antenna wind surface Sec. 65/55 One Rotation 35-62 mm Antenna Hast Diameter 0.5 mm square N Conductor Control Cable 6 Vinyl Cable Max.100Kg.Square Meter(as shown Antenna Fly Wheel effect GD<sup>2</sup> next page)

Dimension Drawing



## SIZE OF USEFUL ANTENNA FOR EMOTATOR AND ANTENNA FLY WHEEL EFFECT

A simple explanation of this should be given here. For example, an autmobile is speeding at a given speed and the transmission is set at "neutral" and you still note that the engine power is not moving the rear two tires, but the autmobile will keep running. This is called the inertia running, and the same effect is present on the rotating antenna system. Once it starts to rotate , even if the power source is cut-off, the antenna and the Emotator will keep rotating for awhile. This is called the Fly wheel effect  $GD^2$ . The antenna system in the fly wheel rotation stage should not be stopped abruptlyasit will generate a big force.

The largeness of the fly wheel effect will depend on the antenna system, the larger antenna, the larger the GD<sup>2</sup>.

The various antennas sold for amateur on the market have the following  $GD^2$ , and antenna wind Surface A.

1	A GD <sup>1</sup>	A GD'	A GD <sup>2</sup>	A GD <sup>2</sup>	A GD'	A GD <sup>2</sup>
	7 M 2 E V p 55 1.0 140	7 M 3 E V p 1.8 455	7 M 2 E F 2.2 750	7 M 3 E F 3 1500	7 M 2 E C Q 2 4 50	7 M 3 E C Q 3 700
HF	14M 3 E F 0.6 70	14M 4 E F 1.2 250	14M 5 E F 1.75 700	14M 6 E F 2.2 1100		
Band	21M 3EF 0.4 100 19	21M 5 E F 0.65 200	0.3 18	21M 2 E H Q 0.4 40	21M 6 E F 1.3 6 25	21M 8 E F 2.5 1600
	28M 4 E F 0.31 90 35	28M 5 E F 0.53 50	28M 2 E H V 0.25 15 14.21M 3 E 0.35 ISO 332	28M 2 E H Q 0.31 35	44	
Huffi	7.14M 3 E V p 0.5 190	7.14M 4 E V p 0.8 200	14.21M 3 E 0.35 ISO 38	14.21M 4 E 0.4 160 48	21.28M 3 E 0.3 130 36	21.28M 4 E 0.3 ISC 44
Band	T 3 E J r 0.3 25	T 3 E 0.4 75	T 4 E 0.5 125	T 6 E 0.55 180	T 2 E C Q 0.5 58	
50MHz	4 E 0.3 3.2	4 E 2 S 0.6 6.4	4 E 2 P 0,6 65	2 E H V 0,2 12	2 E H Q 0.28 30	200
5. S. I	0.35 5 E	07 96 8	5 E 2 P 0.7 3cc 159	6E 0.4 SG 15	0.8 100 39	6 E 2 P 0.8 350 200
	6 E 0.14 1.0	6 E 2 P 0.3 3.5	6 E 2 P 2 S 0.6 7.0	6 E 4 P 0.6 35	6 E 4 P 2 S 1.2 70	
	8E 0.18 2	8E2P 0.35 7	8 E 2 P 2 S 0.8 14	8 E 4 P 0.8 60		
144MHz	10E 0.2 3.5	10E 2 P 0.4 9.5	10E 2 P 2 S 0.8 20	10E 4 P 0.85 65	1.75 1 30	
	12E 0.21 2.5	0.4 10	12E 2 P 2 S 0.85 22	12E 4 P 0.8 70	12E 4 P 2 S 1.8 1 50	
	11E 8 P 1.5 520	0.00	X8E2P 0.45 12	X 10E 0.3 5	X 10E 2 P 0.6 19	
432MHz	10E 0.05 0.35	0.1 1.4	10E 2 P 2 S 0.2 3	0.2 5.8	0.4 12	
	12E 0.06 0.5	12E 2 P 0.1 2	12E 2 P 2 S 0.25 4	12E 4 P 0.3 10	12E 4 P 2 S 0.6 20	

A=Wind Surface M<sup>2</sup>; GD<sup>2</sup>Fly wheel effect Kg.M<sup>2</sup>; E=No.of Element; P=No.of Stack.(Faralel); S=Vertica Stack; CQ=Cubical quaod; HV=HB9CV Antenna; HC=Swiss Quaod; Vp=SHORT beam; Jr=Junia type; W=Wide space; X=Cross Element; T=Tri band antenna;

It is very simple to taking into consideration an antenna system by checking the" GD<sup>2</sup> "and wind surface "A" .

For example the Emotator 103 LBX.

Kind of Antenna	GD <sup>2</sup>	A
Tri band 3 element Jr.type antenna (T3EJr) 144 MHz 10 element Yagi antenna (144M10E) Total Sum		0.3 0.2 0.5
The allowable $GD^2 = 100$ and allowable wind surface	and the second se	and the second se
fore these antenna systems fanction is lower than	Emotato	rs"@ <sup>2</sup> "
and "A" .		



The Antenna mast mounting can categorised in to two systems. A. Mounting system (1) (2) can be mounted directly to the ENO-TATOR mast clamp. This is called the "Independent Mounting System". In this system, the antenna mast length (H) from the EMOTATOR should be kept as short as possible. Where the rotator is to be mounted Fig. (1) it will be necessary to attach the mast clamp model No. 1211 to the under side of rotator.

B. Mounting system Fig. 2 (3. (4) (5) and (6) are mounted in the center of the mast by useing the bearing adapter. This is called the "Rotating Antenna Mast System", when the rotator is installed in a tower, as in this case, it must be fixed tightly with bolts on the rotator mounting plate in the tower. This mounting surface must be perfectly flat, and the top tower hole must be concentric with the axis of rotation of the top part of the Emotator. The example, Pre-determine the surface level when using this Mounting system. As per illustration Fig. 3 if the reclination is more than 1 mm, the mast cannot be mounted and clamped into positions.





If the Emotator is mounted on a reclined position, the mounted Mast will be mounted at an angle (see P) instead of P. This is the reason why it has been stated earlier that the surface must be absolutely level. Dont force the Mast and the Emotator to be installed in this type of position. The 1 mm reclination at the bottom of the Emotator will show approx 20mm misarrengment at the tip of the 2 Meter length mast.

Forcing this type of mounting will cause permanent damage to your Emotator.

Owing to these circumstances, we recommend that our model No.452 Universal Coupling be used to overcome these unforeseen problems.

## ANTENNA MAST CENTER ADJUSTMENT

As per Fig. 4 scale line must be made in line. The figures of 40, 50, 60, at lower position of mast clamp are indication an antenna Mast Diameter (Unit mm). Fig. 4 shows that the Mast diameter is matching to 60 mm.





Connect between rotor section and control section with a 0.5mm square 6-conductor vinyl cable. Process the tip of the cables as per Fig. 6, and connect same number of controller and the terminal board of rotor section.



1. Insert 6-conductor cable through the US plug cap.

2. Insert an each conductor through the US plug pin holes and solder. 3. Cut the tips of the wires protuding from the plug pin tips with a Nipper and screw on cap to plug.

On the other end of cable, insert cable through the waterproof cover, Band and waterproof case.



Between the US plug and the Terminal board, the tips of each wire end must be connected with the same pin number.

### CAUTION

C.

If the different pin number have been connected and supplied electrical power, the Emotator construction parts will be damaged at onece. Please double check if the appropriate wiring have been made.

#### OPERATION



When finished the all of the electrical wiring, please make a theoretical test. By depressing power switch "on" and push the operation switch lever to the Right or to the Left, the rotor section also rotate to the Right or to the Left.

Operation push operation switch lever tp the Right or to the Left and push up to Lock position.

## ADJUSTING THE NEEDLE POINTER DIRECTION AND THE ANTENNA DIRECTION

The direction in which the controller pointer needle stopped automatically will give the indication which way your antenna is facing. If the needle pointer and the antenna direction is not the same, climb your antenna tower and loosen the screw holding the antenna mast and adjust the antenna so that it is in line with the needle pointer.

CAUTION: Do not adjust the direction of the needle pointer of the controller, (the antenna direction must be changed and not the controller's) as the rotation degree will differ.

## CHANGING THE NEEDLE POINTER STANDARD POSITION:

When you wish to change the standard position of the needle pointer of your controller to an appropriate position you wish, remove cover and gently grip the needle pointer with thumb and fore finger and move it to the position that you have selected. The antenna must also be rotated to the exacting position that the needle pointer was moved. Unloosen mast clamp screw and reposition antenna and retighten the screw.

## REPLACING OF MAPS:

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The circle controller has a divided 360 degree installed as the scale plate. For operators requiring Local QSO, a local map should be installed. A local map suitable should be purchased and photo-copied and replaced with the 360 degree scale plate

Remove cover by unloosening the front panel. Gently pull towards you, the needle pointer and it will unloosen easily. Use tweezers and/or a sharp instrument to remove world map from the center hole. (Caution should be taken that the position of the needle pointer be marked before removing the needle pointer.) This is because the needle pointer must be repositioned later at the same position after installing the Local Map.

#### OVERHAUL AND RE+ASSEMBLY

The following cautions must be taken into consideration at the time of Overhauling and Re-Assemble.

1.Brake Rotor Positionning.

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When supplied an electrical Power (AC 24 Volt) to the motor, the motor shaft roate with floating. In this conditions, the Gap of the brake rotor and the brake lining must be fixed about 1 mm by the set screw.

- 2. FOTENTIOMETER ADJUTMENT. As per Photo 1, losen the set screw A<sub>1</sub> to the Gear TS56 rotate freely. In the next, rotate the Gear TS56 to fix the resistance between the terminal board terminal No. 4 and 5 at 80 ohm by using a universal multi meter, and tighten the set Screw A<sub>1</sub>.
- 3. As per photo 2, put the housing and assemble the mark A become to in line with mark B.





Thoto <1>

Photo <2>

#### AN INTERNAL WIRING OF ROTOR

Indicated wire color at this column is a wire color of inside of Rotor. These color discrimination is negessary to overhaul and repair the rotor, and it has no concern with a 6-conductor control cable.

At terminal boaud Terminal No.	l	2	3	4	5	6
Wire Color	Red	Green	Black	Blue	Yellow	White

PARTS LIST PHOTOGRAPH



T S -85T S -74T S -74T S -76T S -76T S -76T S -76T S -76T S -76T S -76 T = 58 T = 58

OPTIONAL ACCESSORIES



Under Side Nast Blacket TS-1211



Mast Bearing 28-65mm 303



Stay Bearing 28-65 mm 300



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Mast Bearing 60-115 mm 350

SPARE PARTS LIST

TS = 11Nast BlacketTS = 56VR GearTS = 12StrapTS = 57N600 ohm PotentiometerTS = 13Gear CaseTS = 58Limit Switch AssyTS = 14Extor CaseTS = 59Flat SpringTS = 15MingTS = 60Stopper LeverTS = 16U BoltTS = 61VR Hanger StrapTS = 16With S.W. 6*20 BoltTS = 65 $6 \times 14$ BoltTS = 18With S.W. 6*20 BoltTS = 65 $6 \times 14$ BoltTS = 29Waterproof CoverTS = 69 $8Pin$ US SocketTS = 319.5 Steel BallTS = 701 Amp. FuseTS = 336P Terminal BoardTS = 72TransformerTS = 36Gear FrameTS = 75ChassisTS = 36Gear FrameTS = 76HousingTS = 46No.1GearTS = 79Operation Switch AssyTS = 46No.1GearTS = 61Needle Pointer CoverTS = 46No.3GearTS = 33(Long shaft) VR PotentionmerTS = 46No.3GearTS = 7830TS = 47No.2GearTS = 78Needle PointerTS = 46No.3GearTS = 62Needle PointerTS = 46No.5GearTS = 62Needle PointerTS = 55VR Counter GearTS = 64Servo NotorTS = 50No.5GearTS = 62Needle PointerTS = 55VR Counter GearTS = 108for foundation8/20 Bolt				Martin and a second
TW = 13Gear CaseTS = 58Limit Switch AssyTS = 14Fotor CaseTS = 59Flat SpringTS = 15RingTS = 60Stopper LeverTS = 16U BoltTS = 61VR Hanger StrapTS = 16With S.W. 6×20 BoltTS = 65 $6 \times 14$ BoltTS = 19With S.W. 8×25 BoltTS = 63 $8Pin$ US PlagTS = 29Waterproof CoverTS = 69 $8Pin$ US SocketTS = 319.5 Steel BallTS = 701 Amp.TS = 33GP Terminal BoardTS = 72TransformerTS = 34Brake LiningTS = 75ChassisTS = 36Gear FrameTS = 76HousingTS = 415×12 ScrewTS = 78Operation KnobTS = 45Brake Rotor PinionTS = 79Operation Switch AssyTS = 46No.1GearTS = 81Needle Pointer CoverTS = 40No.2GearTS = 83(Long shaft) VR PotentionmterTS = 49No.4GearTS = 83(Long shaft) VR PotentionTS = 50No.5GearTS = 85	VR Gear	TS - 56	Mast Blacket	TS - 11
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TE15NingTS60Stopper LeverTS16U BoltTS61VR Hanger StrapTS16With S.W. 6×20 BoltTS64CondenserTS19With SW, RM8×25 BoltTS656×14 BoltTS28Rubber GasketTS668PinUS StocketTS29Waterproof CoverTS698PinUS SocketTS319.5 Steel BallTS701 Amp.FuseTS32Waterproof CaseTS72TransformerTS336P Terminal BoardTS72TransformerTS34Brake LiningTS75ChassisTS35Frame PlateTS75ChassisTS36Gear FrameTS77Front PanelTS40AC 24 VoltNotorTS79Operation KnobTS415×12ScrewTS780TS46No.1GearTS70Needle Pointer CoverTS40No.2GearTS61Needle Pointer CoverTS40No.3GearTS62Needle PointerTS50No.5GearTS63Servo NotorTS50No.5GearTS63Servo NotorTS50No.5GearTS64Servo NotorTS54Servo Notor <t< th=""><th>Limit Switch Assy</th><th>TS - 58</th><th>Gear Case</th><th>TS - 13</th></t<>	Limit Switch Assy	TS - 58	Gear Case	TS - 13
TS = 16 U Bolt TS = 61 VR Hanger Strap TS = 16 With S.W. $6\times 20$ Bolt TS = 64 Condenser TS = 19 With SM, RM $8\times 25$ Bolt TS = 65 $6\times 14$ Bolt TS = 28 Rubber Gasket TS = 68 $8$ Pin US Flag TS = 29 Waterproof Cover TS = 69 $8$ Pin US Socket TS = 31 9.5 Steel Ball TS = 70 1 Amp. Fuse TS = 32 Waterproof Case TS = 71 $8$ Volt Pilot Lanp TS = 33 $6$ P Terminal Board TS = 72 Transformer TS = 34 Brake Lining TS = 73 Servo Mecha. Assy TS = 36 Gear Frame Plate TS = 74 Print Board Assy TS = 38 Spacer TS = 76 Housing TS = 78 $40$ AC 24 Volt Hotor TS = 77 Front Panel TS = 41 $5\times 12$ Screw TS = 78 Operation Switch Assy TS = 46 No.1 Gear TS = 78 Operation Switch Assy TS = 46 No.1 Gear TS = 80 Power Switch TS = 61 WR Hanger Strap	Flat Spring	TS - 59	Notor Case	TS - 14
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TS = 46No.1Gear $TS = 80$ Power Switch $TS = 47$ No.2Gear $TS = 81$ Needle Pointer Cover $TS = 48$ No.3Gear $TS = 82$ Needle Pointer $TS = 49$ No.4Gear $TS = 83$ (Long shaft) VR Potentionmter $TS = 50$ No.5Gear $TS = 84$ $TS = 54$ Servo Motor	Operation Knob	TS - 78	5×12 Screw	TS - 41
TS = 47No.2Gear $TS = 81$ Needle Pointer Cover $TS = 48$ No.3Gear $TS = 82$ Needle Pointer $TS = 49$ No.4Gear $TS = 83$ (Long shaft) VR Potentionmter $TS = 50$ No.5Gear $TS = 84$ $TS = 54$ Servo Motor	Operation Switch Assy		B <b>rake Rotor Pinion</b>	TS - 45
TS = 48No.3GearTS = 82Needle PointerTS = 49No.4GearTS = 83 (Long shaft) VR PotentionmterTS = 50No.5GearTS = 84Servo MotorTS = 54TS = 85Servo Motor	Power Switch	TS - 80	No.l Gear	- TS - 40
TS = 49No.4GearTS = 83 (Long shaft) VRPotentionmterTS = 50No.5GearTS = 84Servo MotorTS = 54TS = 85	Needle Pointer Cover	TS - 81	No.2 Gear	TS - 47
TS = 50 No.5 Gear TS = 84 Servo Motor   TS = 54 TS = 85	Needle Pointer	TS - 82	No.3 Gear	TS - 48
TS - 54 TS - 85	(Long shaft) VR Potentionmter	TS - 83	No.4 Gear	TS - 49
	Servo Motor		No.5 Gear	TS - 50
TS - 55 VR Counter Gear TS -108 for foundation 8×20 Bolt				TS - 54
	for foundation 8×20 Bolt	TS -108	VR Counter Gear	TS - 55

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